

# CS510 Software Engineering

## Program Representations

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<http://nebelwelt.net/teaching/15-CS510-SE>

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# Why Program Representations?

- Original representations: source code, binary, test cases.
- Hard to analyze and bad fit for automatic reasoning.
- Software is translated (lossy or lossless) into certain representations to help certain analyses.

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- 1 Control-Flow Graph
- 2 Cyclomatic Complexity
- 3 Program Dependence Graph
- 4 Super Control-Flow Graph
- 5 Call Graph
- 6 Other Representations and Tools

# Control-Flow Graph (CFG)

- The CFG is an abstract representation of a program that captures all possible flows through the program.
- A CFG is a graph that consists of basic blocks (nodes) and possible control-flow paths (edges).
- A basic block (BB) is a linear sequence of program statements with a single entry and exit. Control-flow cannot exit or halt at any point inside the basic block except at its exit point. Entry and exit nodes coincide if the basic block has only one statement.

# Control-Flow Graph: Definition

## Control-Flow Graph

*A control flow graph (or flow graph)  $G$  is defined as a finite set  $N$  of nodes and a finite set  $E$  of edges. An edge  $(i, j)$  in  $E$  connects two nodes  $n_i$  and  $n_j$  in  $N$ . We often write  $G = (N, E)$  to denote a flow graph  $G$  with nodes given by  $N$  and edges by  $E$ .*

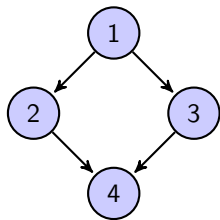
# Control-Flow Graph

- In a CFG, each BB becomes a node and edges are used to indicate the flow of control between blocks.
- An edge  $(i, j)$  connecting blocks  $b_i$  and  $b_j$  implies that control may flow from block  $b_i$  to block  $b_j$ <sup>1</sup>.
- The graph, by convention, also has a *start* node and an *end* node (also in  $N$ ). The start node has no incoming edge while the end node has no outgoing edge.

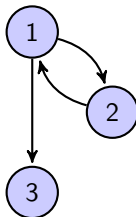
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<sup>1</sup>Note that the graph is directed.

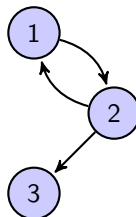
# CFG by Example



if-else condition



for/while loop



do-while loop

# Path

## Path

Consider a flow graph  $G = (N, E)$ . A sequence of  $k$  edges  $k > 0$ ,  $(e_1, e_2, \dots, e_k)$ , denotes a *path* through the flow graph if the following sequence condition holds:

Given that  $n_p, n_q, n_r, n_s$  are nodes belonging to  $N$ , and  $0 < i < k$ , if  $e_i := (n_p, n_q)$  and  $e_{i+1} := (n_r, n_s)$  then  $n_q \equiv n_r$ .

A complete path is a path from start to end. A subpath is a subsequence of a complete path.



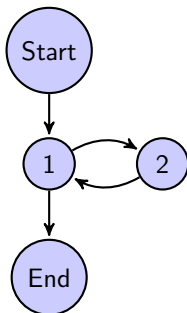
# Feasible Paths

A path  $p$  through a flow graph for program  $P$  is considered *feasible* if there exists at least one test case which when input to  $P$  produces path  $p$ .

```

1 int func(int n) {
2   int i, ret = n;
3   for (i = n-1; i >= 1; i--) {
4     ret = ret * i;
5   }
6 }

```



$$p_1 = (\text{Start}, 1, 2, 1, \text{End})$$

$$p_2 = (\text{Start}, 1, \text{End})$$

$$p_{\text{err}} = (\text{Start}, 1, 2, \text{End})$$

# Number of Paths

- A program may allow many distinct paths, depending on the conditions in the program. A program without conditions contains exactly one path from Start to End.
- Each condition in the program increments the number of paths by at least 1.
- Conditions can have a multiplicative effect on the number of paths.

# Simplified CFG

- Each statement is represented by a node (and each basic block therefore contains only one statement which is the entry and exit statement).
- A simplified CFG is easy to read and implement but not efficient.
- A naive CFG construction algorithm starts with a simplified CFG and merges nodes  $n_i$  and  $n_{i+1}$  iff node  $n_i$  has one outgoing edge and node  $n_{i+1}$  has one incoming edge and edge  $e := (n_i, n_{i+1})$ .

# Dominator

## Dominators

*X dominates Y, iff all possible paths from Start to Y pass through X.*

*X strictly dominates Y, iff X dominates Y and  $X \neq Y$ .*

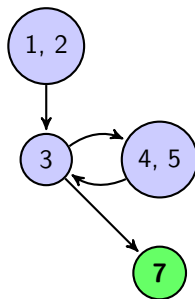
*X immediately dominates Y, iff X dominates Y and X is the last dominator before Y on a path from Start to Y.*

# Dominators: Example

```

1 int sum = 0;
2 int i = 1;
3 while (i < N) {
4     i += 1;
5     sum += i;
6 }
7 printf("Sum: %d", sum);

```



$$sdom(7) = \{1, 2, 3\}$$

$$idom(7) = \{3\}$$

# Post-dominator

## Post Dominators

*X post-dominates Y, iff all possible paths from Y to End pass through X.*

*X strictly post-dominates Y, iff X post-dominates Y and  $X \neq Y$ .*

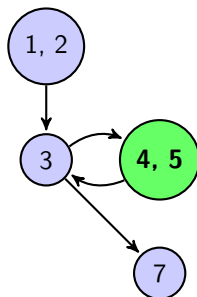
*X immediately post-dominates Y, iff X post-dominates Y and X is the first post-dominator after Y on a path from Y to End.*

# Post-dominators: Example

```

1 int sum = 0;
2 int i = 1;
3 while (i < N) {
4     i += 1;
5     sum += i;
6 }
7 printf("Sum: %d", sum);

```



$$spdom(4, 5) = \{3; 7\}$$

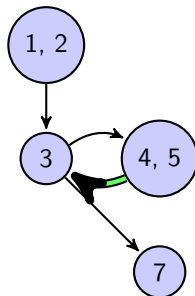
$$ipdom(4, 5) = \{3\}$$

# Backward Edges

```

1  int sum = 0;
2  int i = 1;
3  while (i < N) {
4      i += 1;
5      sum += i;
6  }
7  printf("Sum: %d", sum);

```



A back edge is an edge whose head dominates its tail<sup>2</sup>.

<sup>2</sup>Back edges often identify loops.



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# Cyclomatic Complexity

## Cyclomatic Complexity

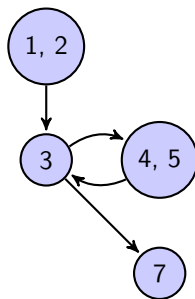
*Cyclomatic complexity is a software metric that measures the quantitative complexity of a program by measuring the number of linearly independent paths through a program's source code. The complexity  $M$  is defined as  $M = E - N + 2P$ , whereas  $E$  is the number of edges,  $N$  the number of nodes, and  $P$  the number of connected components (i.e., functions).*

*Rule of thumb:*

if the complexity  $M$  of a function is larger than 10-15 then the function should be split into multiple components.

# Cyclomatic Complexity: Example

```
1 int sum = 0;
2 int i = 1;
3 while (i < N) {
4     i += 1;
5     sum += i;
6 }
7 printf("Sum: %d", sum);
```



$$E = 4, N = 4, P = 1.$$

$$M = E - N + 2P = 2.$$

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# Program Dependence Graph (PDG)

- Nodes are formed by single statements, not basic blocks.
- *Data-Dependence Graph* used to track data dependencies.
- *Control-Dependence Graph* used to track control dependencies.
- Widely used program representation!

# Data Dependence

## Data Dependence

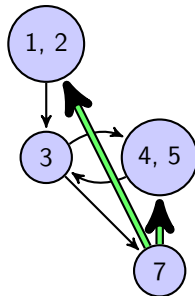
*X is data dependent on Y, iff (i) there is a variable  $v$  defined at Y and used at X and (ii) there exists a path of nonzero length from Y to X along which  $v$  is not redefined.*

# Data Dependence: Example

```

1 int sum = 0;
2 int i = 1;
3 while (i < N) {
4     i += 1;
5     sum += i;
6 }
7 printf("Sum: %d", sum);

```



$DataDep(sum, 7) = \{5, 1\}$

# Difficulties with Data Dependence

Statically computing data dependencies is hard due to aliasing: a variable can refer to multiple memory locations/objects.

```
1 int x, y, z, *p;  
2 x = ...;  
3 y = ...;  
4 p = &x;  
5 p = p + z;  
6 ... = *p;
```



# Control Dependence

## Control Dependence

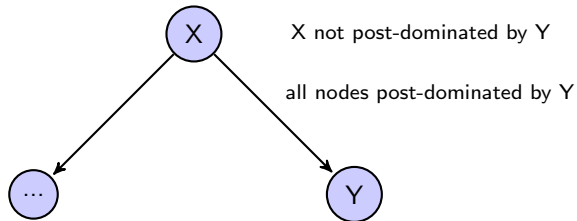
*Y is control dependent on X, iff X directly determines whether Y executes: statements inside one branch of a predicate are usually control dependent on the predicate.*

- there exists a path from X to Y so that every node in the path other than X and Y is post-dominated by Y.  
(No such paths for nodes in a path between X and Y).
- Y does not strictly post-dominate X.  
(There is a path from X to End that does not pass Y or  $X == Y$ ).

Reading assignment:

<http://dl.acm.org/citation.cfm?id=24041>

# Control Dependence: Example



# Using the PDG

A program dependence graph combines the control dependence graph and the data dependence graph of the program.

- In debugging: what statement possibly induced the fault?
- In security: possible redefinitions?

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# Super Control-Flow Graph (SCFG)

- Adds inter-procedural aspects to intra-procedural CFG.
- Connect call sites to entry point of callee.
- Connect return statements back to call site.

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# Call Graph (CG)

- Each node represents a function;
- each edge represents a function invocation.

The CG is useful when reasoning across function boundaries (e.g., for profiling or debugging).

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# Other Representations

- Points-to Graph
- Static Single Assignment (SSA)

# Analysis Tools

- C/C++: LLVM, CIL, CBMC
- Java: SOOT, Wala
- Binary: Valgrind, Pin, Libdetox

# Questions?

?